

Math 1512, Second Exam Practice Problem Set

- Definitions and statements of results:
 - Describe Gauss-Jordan process of finding a row echelon form of a matrix.
 - What are elementary row operations? How can one describe these operations via multiplication by a square matrix on the left?
 - What are the axioms that a determinant function should satisfy?
- Let V and W be linear spaces.
 - Define what it means for a function $T : V \rightarrow W$ to be a *linear transformation*.
 - Define the *image* (= range) of a linear transformation $T : V \rightarrow W$.
 - Let $T : V \rightarrow W$ be a linear transformation, let $\ker(T)$ be the kernel (= null space) of T , and let $\text{im}(T)$ be the image (= range) of T . What does the rank-nullity theorem say about the relationship between the dimensions of the linear spaces $T(V)$, $N(T)$, V , and W ?
 - Define what it means for T to be *onto* and *one-to-one*.

- Let A be the 3×3 matrix

$$A = \begin{pmatrix} 1 & 0 & 1 \\ -1 & 1 & 2 \\ -3 & 1 & 0 \end{pmatrix}$$

- Find a basis for the row space of A .
 - Find a basis for the null space of A .
- Find the reduced row echelon form and the rank of the following matrix:

$$A = \begin{pmatrix} 3 & 1 & 1 & 1 \\ 1 & 2 & -3 & 1 \\ 2 & 1 & 0 & 3 \end{pmatrix}$$

- Consider the system of linear equations

$$x - 2y + az = 2$$

$$x + y + z = 0$$

$$3y + z = 2$$

- For which values of a , if any, does this system have a unique solution?
 - For which values of a , if any, does this system have no solution?
 - For which values of a , if any, does this system have infinitely many solutions?
- Find the dimension and a basis for the subspace of \mathbb{R}^5 consisting of all solutions to the following system of homogeneous linear equations:

$$x + 2y - 4z + 3u - v = 0$$

$$x + 2y - 2z + 2u + v = 0$$

$$2x + 4y - 2z + 3u + 4v = 0$$

7. A linear transformation $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is defined as follows: Each vector (x, y) is reflected across the line $y = x$ and then tripled in length to yield $T(x, y)$.
- Determine the matrix A of T with respect to the ordered basis $v_1 = (1, 1), v_2 = (-1, 1)$ for \mathbb{R}^2 .
 - Determine the matrix B of T with respect to the standard basis $e_1 = (1, 0), e_2 = (0, 1)$ for \mathbb{R}^2 .

8. Let

$$A = \begin{pmatrix} 1 & 0 & 2 \\ 2 & -1 & 3 \\ 4 & 1 & 8 \end{pmatrix}.$$

- Find the inverse of A .
- Find the determinant
 - via Gauss-Jordan;
 - via cofactor expansion.
- Solve $AX = (3, 3, 14)^T$.

9. For

$$F(x) = \begin{vmatrix} f_{11}(x) & f_{12}(x) \\ f_{21}(x) & f_{22}(x) \end{vmatrix}$$

where $f_{ij}(x)$ are differentiable functions, prove that

$$F'(x) = \begin{vmatrix} f'_{11}(x) & f'_{12}(x) \\ f_{21}(x) & f_{22}(x) \end{vmatrix} + \begin{vmatrix} f_{11}(x) & f_{12}(x) \\ f'_{21}(x) & f'_{22}(x) \end{vmatrix}$$

10. Find the least squares approximate solution of the overdetermined system

$$\begin{aligned} x &= 1 \\ 2x - y &= 3 \\ 3x + 5y &= 7 \end{aligned}$$